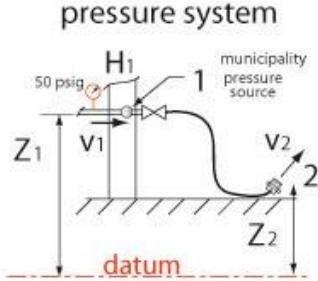


Calculation examples



$$h_P = 0$$

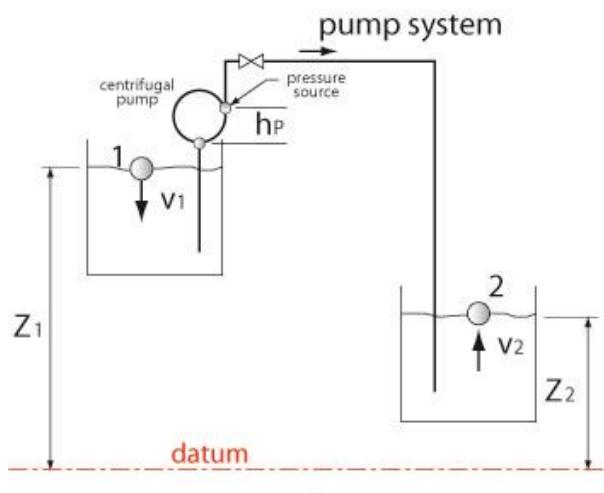
$$H_1 = 50 \times 2.31 = 115 \text{ ft}$$

$$H_2 = 0 \quad v_1 = v_2$$

Goal: calculate v_2

$$\cancel{h_P} + Z_1 + H_1 + \cancel{\frac{v_1^2}{2g}} = \cancel{h_f} + Z_2 + \cancel{H_2} + \cancel{\frac{v_2^2}{2g}}$$

$$Z_1 + H_1 = h_f + Z_2 + \frac{v_2^2}{2g}$$



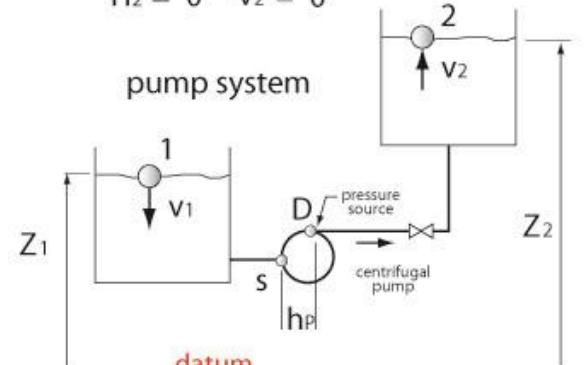
$$H_1 = 0 \quad v_1 \approx 0$$

$$H_2 = 0 \quad v_2 \approx 0$$

Goal: calculate h_P

$$\cancel{h_P} + \cancel{H_1} + Z_1 + \cancel{\frac{v_1^2}{2g}} = h_f + Z_2 + \cancel{H_2} + \cancel{\frac{v_2^2}{2g}}$$

$$h_P + Z_1 = h_f + Z_2$$



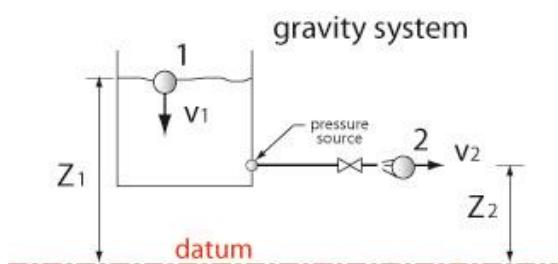
$$H_1 = 0 \quad v_1 \approx 0$$

$$H_2 = 0 \quad v_2 \approx 0$$

Goal: calculate h_P

$$\cancel{h_P} + \cancel{H_1} + Z_1 + \cancel{\frac{v_1^2}{2g}} = h_f + Z_2 + \cancel{H_2} + \cancel{\frac{v_2^2}{2g}}$$

$$h_P + Z_1 = h_f + Z_2$$



$$H_1 = 0 \quad v_1 \approx 0$$

$$H_2 = 0 \quad h_P = 0$$

Goal: calculate v_2

$$\cancel{h_P} + \cancel{H_1} + Z_1 + \cancel{\frac{v_1^2}{2g}} = h_f + Z_2 + \cancel{H_2} + \cancel{\frac{v_2^2}{2g}}$$

$$Z_1 = h_f + Z_2 + \frac{v_2^2}{2g}$$